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In [2] a system of equations for the distribution functions of the first approximation in a partially ionized twotemperature plasma in the presence of a magnetic field was derived using the Chapman-Enskog method [1]. In this article, the part of the distribution function of the first approximation associated with viscosity is found. An expression is obtained for the viscosity tensor for an arbitrarily directed magnetic field.

1. We shall denote the equations of [2] by an asterisk (\*). Factoring out the term with the independent parameter from Eq. (3.3)\*, whose solution was sought in the form (3.6)\*, we obtain

$$f_{a}^{\circ} \frac{m_{a}}{kT_{a}} \left( v_{ai} v_{ak} - \frac{1}{3} v_{a}^{2} \delta_{ik} \right) \frac{\partial c_{0i}}{\partial x_{k}} =$$

$$= f_{a}^{\circ} \frac{e_{a}}{m_{a}c} \varepsilon_{lpq} v_{ap} B_{q} \frac{\partial}{\partial v_{al}} \left( G_{aik} \frac{\partial c_{0i}}{\partial x_{k}} \right) + I_{a} \left( G_{aik} \frac{\partial c_{0i}}{\partial x_{k}} \right).$$

$$(1.1)$$

Here  $f_{\alpha}^{\circ}$  is the Maxwell distribution function for particles of type  $\alpha$ ,  $e_{\alpha}$ ,  $m_{\alpha}$ ,  $T_{\alpha}$  are the charge, mass, and temperature of particles of type  $\alpha$ . The subscript  $\alpha = 1, 2, 3$ , respectively, for singly-charged ions, electrons, and neutral particles;  $B_i$  is the magnetic induction,  $\varepsilon_{ikl}$  a permutation tensor, c the speed of light,  $\nu_{\alpha i}$  the velocity of a particle of type  $\alpha$ ,  $c_{0i}$  the mean mass velocity, and  $G_{\alpha ik}$  is the part of the distribution function associated with viscosity. It is assumed that  $T_1 = T_8 = T \neq T_2$ .

The integrals  $I_{\alpha}$  are given by (3. 4)\*. It is shown in [1] that owing to the structure of Eq. (1. 1) the tensor  $G_{\alpha ik}$  must be symmetric and without divergence, i.e.,

$$G_{aik} = G_{aki}, \qquad G_{aii} = 0. \tag{1.2}$$

From the polar vector  $v_i$  and the axial vector  $B_i$  we can construct five true tensors whose symmetric divergenceless parts will be linearly independent [3, 4].

We shall choose

$$T_{a1ik} = v_{ai}v_{ak} - \frac{1}{3}v_{a}^{2}\delta_{ik}, \qquad T_{a2ik} = B_{i}B_{k}B_{s}B_{i} \left(v_{as}v_{at} - \frac{1}{3}v_{a}^{2}\delta_{sl}\right),$$

$$T_{a3ik} = B_{i}B_{s} \left(v_{ak}v_{as} - \frac{1}{3}v_{a}^{2}\delta_{ks}\right), \qquad T_{a4ik} = B_{i}\varepsilon_{ist} \left(v_{ak}v_{as} - \frac{1}{3}v_{a}^{2}\delta_{ks}\right), \qquad (1.3)$$

$$T_{a5ik} = \varepsilon_{ksl}B_{i}B_{l}B_{l}B_{n} \left(v_{as}v_{an} - \frac{1}{3}v_{a}^{2}\delta_{sn}\right),$$

as the independent tensors and introduce the notation

$$\{T_{ik}\} = \frac{1}{2} \left(T_{ik} + T_{ki} - \frac{2}{3} T_{ij} \delta_{ik}\right).$$
(1.4)

We shall seek a solution of system (1, 1) in the form

$$G_{\alpha ik} = \sum_{\gamma=1}^{5} G_{\alpha\gamma} \{T_{\alpha\gamma ik}\}, \qquad (1.5)$$

It is assumed that  $G_{\alpha\gamma}$  are functions of the scalars  $v_{\alpha}^2$  and  $B^2$ . Substituting (1.5) into (1.1) and carrying out transformations using the rules of tensor algebra [5], we obtain

$$f_{\alpha}^{\circ} \frac{m_{\alpha}}{kT_{\alpha}} T_{\alpha 1 i k} \left\{ \frac{\partial c_{0i}}{\partial x_{k}} \right\} = f_{\alpha}^{\circ} \frac{e_{\alpha}}{m_{\alpha} c} \left\{ \frac{\partial c_{0i}}{\partial x_{k}} \right\} \left[ 2G_{\alpha 1} T_{\alpha 4 i k} + G_{\alpha 3} T_{\alpha 5 i k} + 3G_{\alpha 4} T_{\alpha 3 i k} - 2B^{2}G_{\alpha 4} T_{\alpha 1 i k} + G_{\alpha 5} \left( T_{\alpha 2 i k} - B^{2} T_{\alpha 3 i k} \right) \right] + I_{\alpha} \left( \sum_{\gamma=1}^{5} G_{\alpha \gamma} T_{\alpha \gamma i k} \left\{ \frac{\partial c_{0i}}{\partial x_{k}} \right\} \right),$$

$$(1.6)$$

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We factor out from (1. 6) the coefficients of the following independent parameters:

$$\left\{\frac{\partial c_{0i}}{\partial x_{k}}\right\}, \quad B_{i}B_{k}B_{s}B_{t}\left\{\frac{\partial c_{0s}}{\partial x_{t}}\right\}, \quad B_{i}B_{s}\left\{\frac{\partial c_{0s}}{\partial x_{k}}\right\}, \quad \varepsilon_{sii}B_{t}\left\{\frac{\partial c_{0s}}{\partial x_{k}}\right\}, \quad \varepsilon_{ski}B_{n}B_{t}B_{i}\left\{\frac{\partial c_{0n}}{\partial x_{s}}\right\}, \quad (1.7)$$

and introduce the variables .

$$\eta_{\alpha} = G_{\alpha 1} + iBG_{\alpha 4}, \qquad \lambda_{\alpha} = G_{\alpha 3} + iBG_{\alpha 5}. \qquad (1.8)$$

Then, going over to the dimensionless velocity  $u_{ai} = (m_a / 2kT_a)^{1/2} v_{ai}$ , we obtain the systems of equations:

$$f_{a}^{\circ}\{u_{ai}u_{ak}\} = if_{a}^{\circ} \frac{2e_{a}B}{m_{a}c} \frac{kT_{a}}{m_{a}} \eta_{a} \{u_{ai}u_{ak}\} + \frac{kT_{a}}{m_{a}} I_{a} (\eta_{a} \{u_{ai}u_{ak}\}), \qquad (1.9)$$

$$-f_{a}^{\circ} \frac{e_{a}}{m_{a}c} 3G_{a4} \{u_{ai}u_{ak}\} = if_{a}^{\circ} \frac{e_{a}B}{m_{a}c} \lambda_{a} \{u_{ai}u_{ak}\} + I_{a} (\lambda_{a} \{u_{ai}u_{ak}\}), \qquad (1.10)$$

$$-f_{\alpha}^{\circ} \frac{e_{\alpha}}{m_{\alpha}c} G_{\alpha b} \{u_{\alpha i}u_{\alpha k}\} = I_{\alpha} \left( G_{\alpha b} \{u_{\alpha i}u_{\alpha k}\} \right).$$
(1.11)

Systems (1.9)-(1.11) must be solved successively. However, from (1.6) it is easy to obtain the equation

$$f_{a}^{\circ} \frac{m_{a}}{kT_{a}} \{ v_{ai} v_{ak} \} = I_{a} \left[ \left( G_{a1} + \frac{2}{3} B^{2} G_{a3} + \frac{2}{3} B^{4} G_{a2} \right) \{ v_{ai} v_{ak} \} \right].$$

The quantity  $G_{\alpha 1} + \frac{2}{3}B^2G_{\alpha 3} + \frac{2}{3}B^4G_{\alpha 2}$  satisfies the same equation obtained for  $G_{\alpha 1}$  when B = 0. Consequently,

$$(G_{\alpha 1})_{B=0} = G_{\alpha 1} + \frac{2}{3}B^2 G_{\alpha 3} + \frac{2}{3}B^4 G_{\alpha 2} .$$
(1.12)

Thus, we may use (1.12) to find  $G_{\alpha 2}$  instead of the solution to (1.11). Following [1], we will seek  $G_{\alpha \gamma}$  in the form of a series expansion in Sonine polynomials  $S_{s_{12}}^{(p)}(x)$ , defined as [1]:

$$(1-s)^{-1/2} \exp \frac{-xs}{1-s} = \sum_{p=0}^{\infty} S_{b/s}^{(p)}(x) s^{p} , \qquad (1,13)$$

$$\int_{0}^{\infty} S_{s/2}^{(p)}(x) S_{s/2}^{(q)}(x) e^{-x} x^{s/2} dx = \frac{\Gamma(7/2 + p)}{p!} \delta_{pq} .$$
(1.14)

We have

$$G_{\alpha\gamma} = \sum_{p=0}^{\infty} g_{\alpha\gamma p} S_{b/z}^{(p)} (u_{\alpha}^{2}) .$$
 (1.15)

For  $v_{\alpha p} = g_{\alpha 1 p} + i B g_{\alpha 4 p}$ , we obtain the infinite system of linear algebraic equations

$$\frac{5}{2} n_{\alpha} \delta_{0p} = i \omega_{\alpha} \frac{kT_{\alpha}}{m_{\alpha}} n_{\alpha} \frac{8}{3 \sqrt{\pi}} \frac{\Gamma \left(p + \frac{7}{2}\right)}{p!} v_{\alpha p} + \frac{kT}{m_{1}} \sum_{r=0}^{\infty} b_{pr}^{\alpha 1} v_{1r} + \frac{kT_{2}}{m_{2}} \sum_{r=0}^{\infty} b_{pr}^{\alpha 2} v_{2r} + \frac{kT}{m_{3}} \sum_{r=0}^{\infty} b_{pr}^{\alpha 3} v_{3r} \qquad (\alpha = 1, 2, 3; p \ge 0; \omega_{\alpha} = \frac{e_{\alpha}B}{m_{\alpha}c})$$
(1.16)

by substituting the expansion (1. 15) into (1. 9), multiplying the obtained expression by  $S_{s/2}^{(p)}(u_{\alpha}^{2}) \{u_{\alpha i}u_{\alpha k}\}$ , integrating with respect to  $dc_{ai}$ , and using the fact that the Sonine polynomials (1. 14) are orthogonal.

The values of  $b_{pq}^{\alpha\beta}$  are determined in the following manner:

$$b_{pq}^{\alpha\alpha} = \int f_{\alpha}^{\circ} f^{\circ} S_{b_{2}}^{(p)}(u_{\alpha}^{2}) \{u_{\alpha i} u_{\alpha k}\} [S_{b_{2}}^{(q)}(u_{\alpha}^{2}) \{u_{\alpha i} u_{\alpha k}\} + S_{b_{2}}^{(q)}(u^{2}) \{u_{i} u_{k}\} - S_{b_{2}}^{(q)}(u^{2}) \{u_{\alpha i}^{\prime} u_{\alpha k}^{\prime}\} - S_{b_{2}}^{(q)}(u^{2}) \{u_{i}^{\prime} u_{k}^{\prime}\}] g_{\alpha\alpha} b \, db \, dc \, dc_{i} dc_{\alpha i} + \sum_{\beta \neq \alpha} \int S_{b_{2}}^{(p)}(u_{\alpha}^{2}) \{u_{\alpha i} u_{\alpha k}\} [f_{\alpha}^{\circ} f_{\beta}^{\circ} S_{b_{2}}^{(q)}(u_{\alpha}^{2}) \{u_{\alpha i} u_{\alpha k}\} - f_{\alpha}^{\circ'} f_{\beta}^{\prime \circ} S_{b_{2}}^{(q)}(u_{\alpha}^{\prime}) \{u_{\alpha i}^{\prime} u_{\alpha k}^{\prime}\}] g_{\alpha\beta} b \, db \, dc \, dc_{\beta i} \, dc_{\alpha i} , \qquad (1.17)$$

$$b_{pq}^{\alpha\beta} = \int S_{s_{a}}^{(p)} (u_{\alpha}^{2}) \{ u_{\alpha i} u_{\alpha k} \} [f_{\alpha}^{\alpha} f_{\beta}^{\alpha} S_{s_{a}}^{(q)} (u_{\beta}^{2}) \{ u_{\beta i} u_{\beta k} \} - (1, 17)$$
  
-  $f_{\alpha}^{\alpha'} f_{\beta}^{\alpha'} S_{s_{a}}^{(q)} (u_{\beta}^{\prime 2}) \{ u_{\beta i}^{\prime} u_{\alpha k}^{\prime} \} ] g_{\alpha \beta} b d b d e d c_{\alpha i} d c_{\alpha i} (\alpha, \beta = 1, 2, 3; \alpha \neq \beta).$ 

Similarly, for the coefficients  $\mu_{ap} = g_{a3p} + iBg_{a5p}$ , we obtain from (1.10) and (1.15)

$$-\frac{4}{\sqrt{\pi}} \frac{\Gamma(p+7/2)}{p!} n_{\alpha} \frac{e_{\alpha}}{m_{\alpha}c} g_{\alpha 4p} = i \frac{4}{3\sqrt{\pi}} \frac{\Gamma(p+7/2)}{p!} \omega_{\alpha} n_{\alpha} \mu_{\alpha p} + \frac{m_{\alpha}T}{m_{1}T_{\alpha}} \sum_{r=0}^{\infty} b_{pr}^{\alpha 1} \mu_{1r} + \frac{m_{\alpha}T_{2}}{m_{2}T} \sum_{r=0}^{\infty} b_{pr}^{\alpha 2} \mu_{2r} + \frac{m_{\alpha}T}{m_{3}T_{\alpha}} \sum_{r=0}^{\infty} b_{pr}^{\alpha 3} \mu_{3r} \quad (\alpha = 1, 2, 3; p \ge 0).$$
(1.18)

For the coefficients  $g_{\alpha 2p}$ , we obtain from (1.12)

$${}^{2}/_{3}B^{4}g_{a2r} = (g_{a1r})_{B=0} - {}^{2}/_{3}B^{2}g_{a3r} - g_{a1r} .$$
(1.19)

Systems (1. 16) and (1. 18) are solved successively using the Cramer rule.

2. By definition [1], the viscous stress tensor is

$$\pi_{aik} = \Pi_{aik} - p_a \delta_{ik} \,. \tag{2.1}$$

Making use of the definition of  $\Pi_{\alpha ik}$  and  $P_{\alpha}$  in (1.9)\* and (3.1)\*, we obtain

$$\pi_{\alpha ik} = n_{\alpha} m_{\alpha} \langle v_{\alpha i} v_{\alpha k} - \frac{1}{3} v_{\alpha}^{2} \delta_{ik} \rangle.$$
(2.2)

Only the term with  $G_{aik}$  makes a contribution to the viscous stress tensor  $\pi_{aik}$  [1]. Using the definitions (2.2) and (1.9)\*, the expansions (3.6)\* and (1.15), the fact that the Sonine polynomials in (1.14) are orthogonal, and the relationship

$$\int \varphi(v) \{v_{i}v_{k}\} \{v_{p}v_{q}\} dc_{i} = \frac{1}{15} \left( \delta_{ip} \delta_{kq} + \delta_{iq} \delta_{kp} - \frac{2}{3} \delta_{ik} \delta_{pq} \right) \int \varphi(v) v^{4} dc_{i} , \qquad (2.3)$$

which is easily verifiable for the isotropic function  $\varphi(\nu)$ , we obtain

$$\pi_{aik} = -2\mu_{aikpq} \left\{ \frac{\partial c_{0R}}{\partial x_q} \right\} \qquad \mu_{aikpq} = \frac{(kT_{a})^2}{m_{a}} n_a \left[ g_{a10} \delta_{ip} \delta_{kq} + g_{a20} \left( B_i B_k - \frac{1}{3} \delta_{ik} B^2 \right) B_p B_q + \frac{1}{2} g_{a30} \left( B_i B_p \delta_{kq} + B_k B_p \delta_{iq} - \frac{2}{3} \delta_{ik} B_p B_q \right) + \frac{1}{2} g_{a40} \left( \varepsilon_{pil} B_l \delta_{qk} + \varepsilon_{pkl} B_l \delta_{qi} \right) + \frac{1}{2} g_{a50} \left( \varepsilon_{qil} B_p B_l B_k + \varepsilon_{qkl} B_p B_l B_l \right) \right].$$
(2.4)

The quantity  $\mu_{dikpq}$  is the viscosity tensor for  $\alpha$ -type particles in a magnetic field. A general expression for the viscosity tensor for an arbitrarily directed magnetic field was obtained by taking the system of independent tensors in the form (1.3). In [6] a general expression was not obtained for the viscosity tensor, another system of independent tensors being chosen. To find the viscosity tensor, it is necessary to know only the first coefficient in (1.15).

3. We leave a single Sonine polynomial in expansions (1.15). The quantities  $b_{00}^{\alpha\beta}$ , given by (1.17), have the form

$$b_{00}^{11} = \frac{3n\alpha}{\tau_1} + \frac{y_1}{\tau_{13}} n\alpha (1 - \alpha), \qquad b_{00}^{13} = b_{00}^{31} = -\frac{y_2}{\tau_{13}} n\alpha (1 - \alpha),$$

$$b_{00}^{22} = \left(\frac{3}{\sqrt{2}} + 3\right) \frac{n\alpha}{\tau_2} + \frac{y_3}{\tau_{23}} n\alpha (1 - \alpha),$$

$$b_{00}^{33} = \frac{n(1 - \alpha)}{\tau_3} + \frac{y_1}{\tau_{13}} n\alpha (1 - \alpha), \qquad b_{00}^{12}, \ b_{00}^{21} \sim \frac{m_2}{m} \frac{n\alpha}{\tau_2} \qquad b_{00}^{32}, \ b_{00}^{23} \sim \frac{m_2}{m} \frac{n\alpha (1 - \alpha)}{\tau_{33}}$$
(3.1)

if we ignore quantities  $\sim (m_2 / m)^{1/2}$  in comparison with unity.

To compute (3. 1) conditions (5. 7)\* were used. The quantities  $\tau_{\alpha}$  and  $\tau_{\alpha}\beta$  are given by (5. 2)\*. The structure of systems (1. 16) and (1. 18) is such that, if we neglect quantities  $\sim (m_2 / m)^{1/4}$  in comparison with unity, we do not need

to know the elements  $b_{00}^{32}$  and  $b_{00}^{23}$  exactly, since due to their smallness they do not appear in the final results. For Maxwellian interaction between neutral and charged particles, we have

$$y_1 = 8.32, \quad y_2 = 1.06, \quad y_3 = 10.3.$$
 (3.2)

For any interaction, we have the relations [1]:

$$\frac{y_1}{n\tau_{13}} = \frac{4}{3} \left[ 5\Omega_{13}^{(1)}(1) + \frac{3}{2} \Omega_{13}^{(2)}(2) \right] \qquad \frac{y_3}{n\tau_{23}} = 8\Omega_{23}^{(2)}(2)$$

$$\frac{y_2}{n\tau_{13}} = \frac{4}{3} \left[ 5\Omega_{13}^{(1)} - \frac{3}{2} \Omega_{13}^{(2)}(2) \right].$$
(3.3)

Here  $\Omega_{\beta3}^{(l)}(p)$  are given by (5.9)\*. The temperature ratio for electrons and heavy particles is always linearly dependent on the mass ratio and, being much smaller than the ratio of the masses of the heavy particles and electrons, does not affect the order of the elements  $b_{00}^{\alpha2}$  and  $b_{00}^{3\alpha}$  ( $\alpha = 1, 3$ ). The limitation on the temperature ratio follows from the conditions of applicability of the Boltzmann equations [7]. The solution of system (1, 16), taking into account (3.1), has the form

$$g_{116} = \frac{5}{6} \frac{m}{kT} \tau_1 \Gamma_1 \frac{1 + y_2 (1 - \alpha) (\tau_3 / \tau_{13} + y_1 \alpha \tau_3)}{\Gamma_1^2 + \frac{25}{9} \omega_1^2 \tau_1^2},$$

$$g_{140} = -\frac{25}{18} \frac{m}{kT} \tau_1 \frac{\omega_1 \tau_1}{B} \frac{1 + y_2 (1 - \alpha) (\tau_3 / \tau_{13} + y_1 \alpha \tau_3)}{\Gamma_1^2 + \frac{25}{9} \omega_1^2 \tau_1^2},$$

$$g_{310} = \frac{5}{2} \frac{m}{kT} \tau_3 \frac{\Gamma_1 \Gamma_2 + (\frac{25}{9}) \omega_1^2 \tau_1^2}{[\Gamma_1^2 + \frac{25}{9} \omega_1^2 \tau_1^2] [1 + y_1 \alpha (\tau_3 / \tau_{13})]},$$

$$g_{340} = \frac{25}{6} \frac{m}{kT} \tau_3 \frac{\Gamma_1 - \Gamma_2}{[\Gamma_1^2 + \frac{25}{9} \omega_1^2 \tau_1^2] [1 + y_1 \alpha (\tau_3 / \tau_{13})]},$$

$$g_{310} = \frac{5}{3(2 + \sqrt{2})} \frac{m_2 \tau_2}{kT_2} \frac{1 + [2y_3 (1 - \alpha) \tau_2 / 3 (2 + \sqrt{2}) \tau_{23}]}{[1 + [2y_3 \tau_1 (1 - \alpha) \tau_2 - (1$$

where

$$\Gamma_{1} = 1 + \frac{y_{3}\tau_{1}(1-\alpha)}{3\tau_{13}} - \frac{y_{2}^{2}\tau_{1}\tau_{3}\alpha(1-\alpha)}{\tau_{13}^{2}[1+y_{1}\alpha(\tau_{3}/\tau_{13})]}, \quad \Gamma_{2} = 1 + \frac{y_{1}\tau_{1}(1-\alpha)}{3\tau_{13}} + \frac{y_{2}\tau_{1}\alpha}{3\tau_{3}}. \quad (3.5)$$

Using (3, 1) and (3, 4), we obtain the solution of system (1, 18) in the form

$$g_{130} = \frac{25}{6} \frac{\omega_1^2 \tau_1^2}{B^2} \frac{g_{110}}{\Gamma_1^2 + \frac{25}{36}\omega_1^2 \tau_1^2}, \qquad g_{150} = \frac{25}{12} \frac{\omega_1^2 \tau_1^2}{B^2} \frac{g_{140}}{\Gamma_1^2 + \frac{25}{36}\omega_1^2 \tau_1^2},$$

$$g_{330} = \frac{25}{6} \frac{\omega_1^2 \tau_1^2}{B^2} \frac{y_2 (1 - \alpha) (\tau_3 / \tau_{13} + y_1 \alpha \tau_3) g_{110}}{\Gamma_1^2 + \frac{25}{36}\omega_1^2 \tau_1^2},$$

$$g_{350} = \frac{25}{12} \frac{\omega_1^2 \tau_1^2}{B^2} \frac{y_2 (1 - \alpha) (\tau_3 / \tau_{13} + y_1 \alpha \tau_3) g_{140}}{\Gamma_1^2 + \frac{25}{36}\omega_1^2 \tau_1^2},$$

$$g_{330} = \frac{25}{3 (1 + \sqrt{2})^2} \frac{\omega_2^2 \tau_2^2}{B^2} g_{210} \left\{ \left[ 1 + \frac{2y_3 (1 - \alpha) \tau_2}{3 (2 + \sqrt{2}) \tau_{23}} \right]^2 + \frac{25}{9 (2 + \sqrt{2})^2} \omega_2^2 \tau_2^2 \right\}^{-1},$$

$$g_{250} = \frac{25}{6 (1 + \sqrt{2})^2} \frac{\omega_2^2 \tau_2^2}{B^2} g_{240} \left\{ \left[ 1 + \frac{2y_3 (1 - \alpha) \tau_2}{3 (2 + \sqrt{2}) \tau_{23}} \right]^2 + \frac{25}{9 (2 + \sqrt{2})^2} \omega_2^2 \tau_2^2 \right\}^{-1}.$$
(3.6)

The coefficients  $g_{\alpha 20}$  are found from (1, 19):

$$g_{a20} = \frac{3}{2B^4} (g_{a10})_{B=0} - \frac{1}{B^2} g_{a30} - \frac{3}{2B^4} g_{a10} .$$
(3.7)

From (3. 4)-(3. 7) with  $\alpha = 1$  and a magnetic field directed along the x-axis, for the ion stress tensor  $\pi_{1ik}$ , we obtain the relations of [1] with the corrections made in [6]. For  $\alpha = 0$ , we obtain the first-approximation formula for the viscosity coefficient of a simple gas [1]

$$\mu_{3} = \frac{5}{16} \frac{\sqrt{kmT}}{\sqrt{\pi} \sigma^{2}} \frac{1}{\Omega^{(2,2)*}}$$
(3.8)

from the expression for  $g_{310}$  taking into account (5. 2)\* and (2. 5).

For an elastic ball model  $\Omega^{(3,3)} = 1$ .

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